Deepview: Virtual Disk Failure Diagnosis and Pattern Detection for Azure

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Compute-Storage Separation

- Virtual hard disks (VHDs) and VMs on different physical clusters
- Easy VM migration when VMs are unavailable
 - Can create VM on different host/cluster
 - Simply attach VHD
- Load balancing through many-to-many relationship
 - Many VMs can use the same VHD
 - One VM can use multiple VHDs
- VHD driver in hypervisor level send RPCs to storage service

VHD Failure

- In Azure, shutdown guest OS if unresponsive for 2 minutes
 - Mainly to protect data integrity
 - Notify the customers of VHD access failure
 - Maintain customers' SLAs

VHD Failure	SW Failure	HW Failure	Unknown	
52%	41%	6%	1%	

Table 1: Breakdown of the causes of VM downtime. VHD failures cause the majority of VM downtime.

Previous Approach

- SREs examined different parts of the system
 - Compute team, storage team, and network team
- 10s of minutes or sometimes hours to localize the failure
- One network failure led to 363 incidents
 - Incident was moved from one team to another
- In short, not accurate and not efficient

Bipartite Model



Figure 3: The bipartite model and the corresponding matrix view of a downtime event.

Goals of the Paper

- Stronger granularity
 - Simple bipartite model does not work for multi-tier networks
- Detection of Gray failures
- Fast detection
 - Aim for 15 minutes (availability objective)

Model - Network

- Represent Clos topology as tree
 - Start from Top-of-Rack switches
 - Group every Tier 1 switch that connects to ToR
 - Group every Tier 2 switch that connects to T1 switch
 - $\circ \quad \text{ And so on....}$
 - Finally, determine midpoint by collecting shortest paths
- Discussion: Valid approach?

Model - Network



Derivation of Probabilities

 $\mathbb{P}(\text{path i is fine}) = \prod_{j \in \text{path}(i)} \mathbb{P}(\text{component j is fine})$

Derivation of Probabilities

$$\frac{n_i - e_i}{n_i} \approx \prod_{j \in \text{path}(i)} p_j$$

 n_i is the number of VMs e_i is the number of VMs with VHD failures for a given period p_i is the probability that the path is fine

Next step: Model approximation with noise and create system of equations

Derivation of Probabilities



Interpretation of Equations

- A significantly negative B_i usually suggests to blame that component
- Necessity to modify data
 - Failures are normally independent from each other
 - Array of B should theoretically be mostly 0's
 - Apply Lasso estimate with a parameter λ (black-box)
 - Tradeoff: goodness-of-fit versus sparsity

$$\hat{\boldsymbol{\beta}} = \underset{\boldsymbol{\beta} \in \mathbb{R}^{N}, \boldsymbol{\beta} \leq \boldsymbol{0}}{\arg\min} \| \mathbf{y} - \mathbf{X}\boldsymbol{\beta} \|_{2}^{2} + \lambda \| \boldsymbol{\beta} \|_{1}.$$

Hypothesis Testing

- 1. Define a z-score from the mean and standard deviation of a value
- 2. Compute the p-value
 - In this paper, assume Gaussian distribution
 - Is this a safe assumption?
- 3. Make decision based on the p-value
 - If the p-value is less than 1%, blame the component

Deepview System

- Non-real-time information
 - Network topology, account information, compute-storage
 - Periodic snapshots every few hours
 - Sufficient?
- Real-time information
 - VHD failures send signals
 - Implement a streaming system

Deepview System



Table Name	Schema		
VHDFailure	(ts, vm_id, vhd, str_account)		
VMInfo	(ts, vm_id, comp_cluster, tor)		
StorageAccount	(ts, str_account, str_cluster)		
NetworkTopo	(ts, cluster, tor_list, t1_list,		
	t2_list, t3_list)		
VMsPerPath	(tstart, tend, num_vms)		
ClusterRawData	(tstart, tend, comp_cluster,		
	str_cluster, num_vms,		
	num_failed_vms)		
TorRawData	(tstart, tend, comp_cluser,		
	tor, str_cluster, num_vms,		
	num_failed_vms)		
FailurePattern	(tstart, tend, region, type, loc,		
	pval, visual_url)		

Deepview System

- Computation DAG
- NRT Scheduler
- Sparse Matrix/Region Filtering
 - Used to reduce runtime
- Coordinate Descent
 - One of the fastest ways to solve Lasso regression
- Cross-validation for λ

Evaluation: ToR Reboot

- All VMs communicate with a single ToR
 - Failure means lack of communication with VHD
- Deepview predicts and verifies prediction
- Chose the correct ToR out of 288 components
 - p-value much less than 0.01

Evaluation: Storage Gray Failure

- At hour 0, three components with failure probability > 0
 - Storage cluster S0 0.34
 - Compute cluster C0 0.002
 - Compute cluster C1 0.047
- Only S0 corresponded to p-value less than 1%
- Similar case for network failures

Other Algorithms

- Boolean-Tomo and SCORE
 - Greedy algorithms
 - Goal: Identify bad paths based on threshold
 - Iterative discovery or computation
- Approximate Bayesian Network
 - Exponential runtime
 - Lack of meaningful results

Precision and Recall



Figure 10: Precision/Recall comparison.

	Compute	Storage	Net	ToR
Precision	0.85	0.875	1.0	1.0
Recall	1.0	1.0	1.0	1.0

Table 3: Precision/Recall by failure type for Deepview.

How well does it perform?

- Lasso regression
 - Impossible to find universally optimal Lambda
- Hypothesis testing
 - Even with low failure probability, hypothesis testing works
 - Example: Storage cluster gray failure case
- Runtime of Deepview
 - Worst-case: 18.3 seconds
- TTD: under 10 minutes

ToR - Single-point-of-Failure

- Questions about ToR as bottleneck for availability
- Deepview detects ToR failure
 - More data!
- First, <0.1% of switches experience ToR reboots
- Second, 90% of reboots are soft

$$1 - \frac{0.9 \times 20 + 0.1 \times 120}{1000 \times 30 \times 24 \times 60} = 99.99993\%$$

Network Path

- Distribution of network path
 - $\circ ~~51.4\%\,go\,up\,to\,T2$
 - $\circ \quad 41.0\%\,go\,up\,to\,T3$
 - Rest go beyond
- Leverage Deepview data
- 11.4% increase in VHD failure rate with T3 or above
- Maybe beneficial to keep VHD and VM close

Machine Learning

- Can a ML approach work in this situation?
- Possible weakness: Need richer signals
- Paper mentions NetPoirot
 - Features: TCP statistics
 - Labels: failure locations
 - Complementary
- BUT can a ML approach replace or outperform Deepview?

Pros and Cons

Pros:

- Application of simple statistical ideas in a real-world system problem
- Presentation of valuable lessons learned through the data acquired in Deepview

Cons:

- Some parts of the model have to be inferred through reading different parts (could have been more clear)
- Lack of discussion on more examples of cases

References

Figures, equations, and content used from:

Qiao Zhang, Guo Yu, Chuanxiong Guo, Yingnong Dang, Nick Swanson, Xinsheng Yang, Randolph Yao, Murali Chintalapati, Arvind Krishnamurthy, and Thomas Anderson. 2018. Deepview: virtual disk failure diagnosis and pattern detection for azure. In *Proceedings of the 15th USENIX Conference on Networked Systems Design and Implementation (NSDI'18)*. USENIX Association, USA, 519–532.